# Resolution-Aware Fitting of Active Appearance Models to Low-Resolution Images

#### Problem

Active Appearance Models (AAM) are compact representations of the shape and appearance of objects. [Cootes et al, '98]. Fitting AAMs to images is a difficult, nonlinear optimization task. Traditional approaches can fit well to high-resolution images, but they degrade quickly at lower resolutions. We diagnose why this is the case, and propose a remedy.

# Background

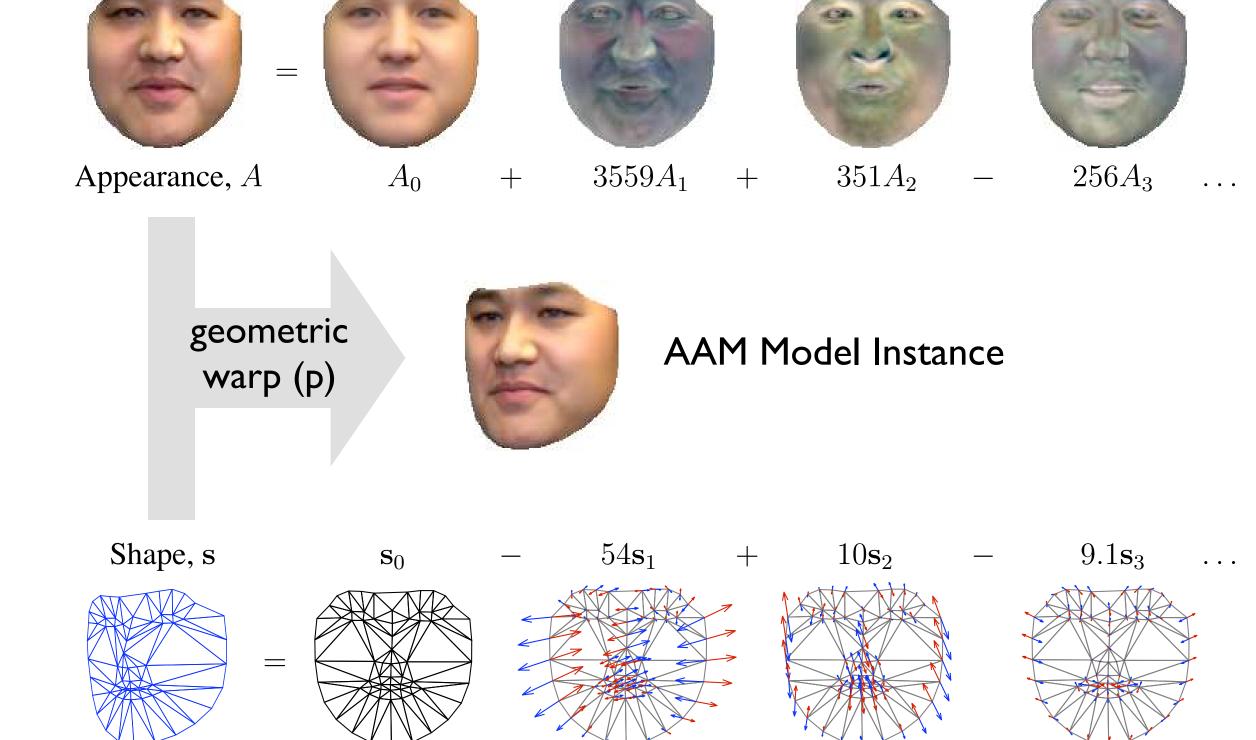
An AAM has two components: shape and appearance. Each is a linear, Principal Components model learned via training.

The shape is defined by a set of landmarks. In addition to non-rigid shape modes, four special basis shapes account for similarity transforms.

The appearance component is shapenormalized.

Fitting algorithms aim to recover those parameters which best explain a given image.

$$\mathbf{s} = (x_1, y_1, x_2, y_2, \dots, x_v, y_v)^{\mathrm{T}}$$
 $\mathbf{s}(\mathbf{p}) = \mathbf{s}_0 + \sum_{i=1}^n p_i \mathbf{s}_i \quad \text{where} \quad \mathbf{p} = (p_1, p_2, \dots, p_n)$ 



from [Matthews and Baker, '04]

#### Traditional Formulation

Fit the AAM by minimizing the L2 norm error between the model instance and the input image warped onto the model coordinate frame.

Objective function:

AAMR-SIM

$$\sum_{\mathbf{x} \in \mathbf{s}_0} \left[ I(\mathbf{W}(\mathbf{x}; \mathbf{p})) - A(\mathbf{x}; \boldsymbol{\lambda}) \right]^2$$

The "simultaneous inverse compositional" fitting algorithm [Gross et al., '05] iteratively solves for the shape and appearance updates.

Gauss-Newton gradient descent:

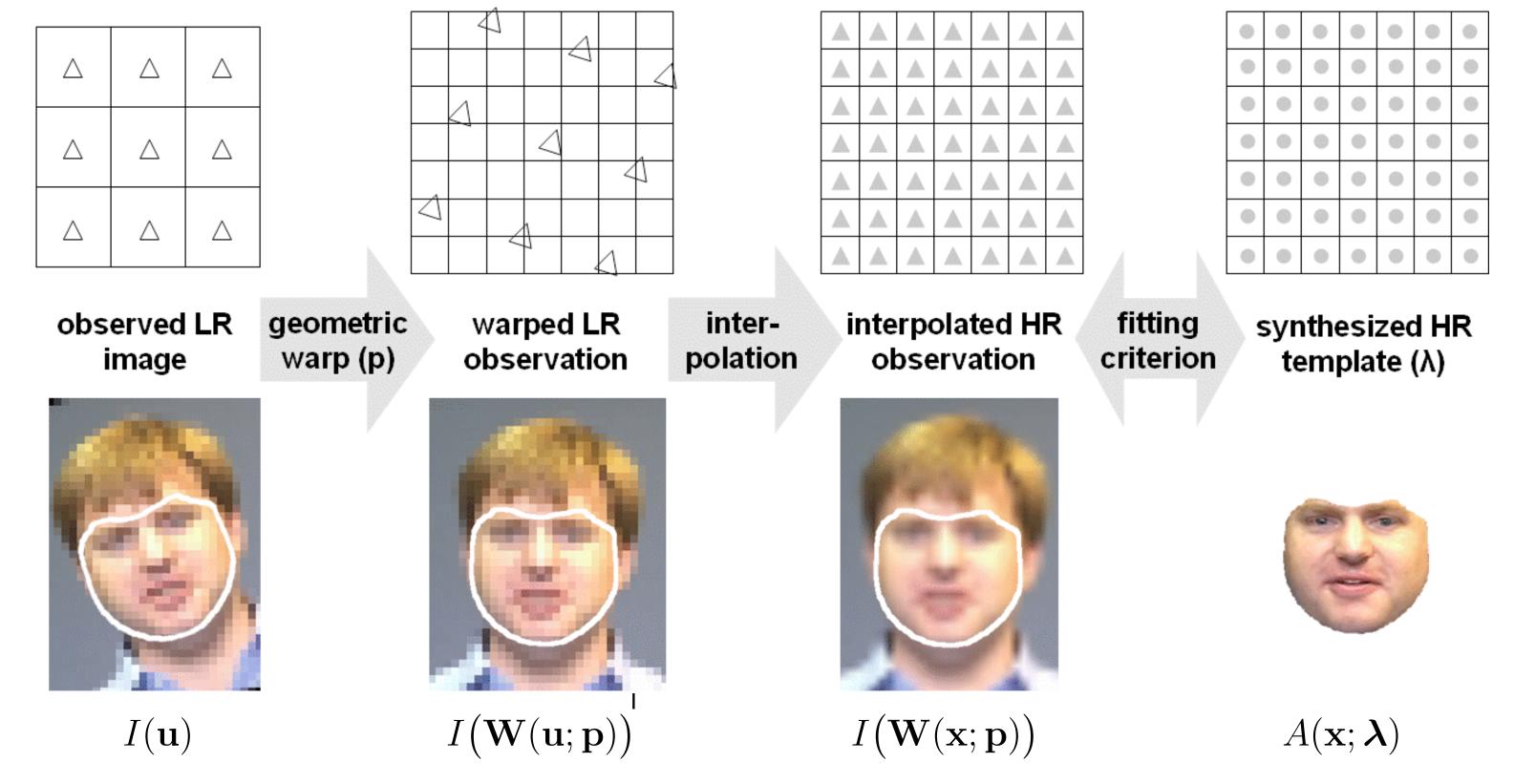
$$\begin{pmatrix} \Delta \mathbf{p} \\ \Delta \boldsymbol{\lambda} \end{pmatrix} = -H_{\text{sim}}^{-1} \sum_{\mathbf{x}} \mathbf{S} \mathbf{D}_{\text{sim}}^{\text{T}}(\mathbf{x}) \left[ I(\mathbf{W}(\mathbf{x}; \mathbf{p})) - A(\mathbf{x}; \boldsymbol{\lambda}) \right]$$

$$\mathbf{SD}_{\mathrm{sim}}(\mathbf{x}) = \left( \nabla A \frac{\partial \mathbf{W}}{\partial p_1}, \dots, \nabla A \frac{\partial \mathbf{W}}{\partial p_n}, A_1(\mathbf{x}), \dots, A_m(\mathbf{x}) \right)$$

$$H_{\mathrm{sim}} = \sum_{\mathbf{x}} \mathbf{S} \mathbf{D}_{\mathrm{sim}}^{\mathrm{T}}(\mathbf{x}) \mathbf{S} \mathbf{D}_{\mathrm{sim}}(\mathbf{x})$$

Inverse-compositional warp update:

$$\mathbf{W}(\mathbf{x}; \mathbf{p}) \leftarrow \mathbf{W}(\mathbf{x}; \mathbf{p}) \circ \mathbf{W}(\mathbf{x}; \Delta \mathbf{p})^{-1}$$



From left to right, observed images get warped, interpolated, and finally compared against the synthesized model instance. When the input image is low in resolution, significant interpolation is needed to warp it onto the model coordinate frame.

## Resolution-Aware Formulation

We explicitly account for the finite size sensing elements of digital cameras, and simultaneously model the processes of object appearance variation, geometric deformation, and image formation.

Objective function:

RAF

$$\sum_{\mathbf{u}\in I} \left[ I(\mathbf{u}) - B(\mathbf{u}; A(\mathbf{W}(\mathbf{p}); \boldsymbol{\lambda})) \right]^2$$

The blur model can incorporate arbitrary cameras and point spread functions (PSF). We use the rectangular PSF:

$$B(\mathbf{u}; A(\mathbf{W}(\mathbf{p}); \boldsymbol{\lambda})) = \frac{1}{area(\mathbf{u})} \int_{\mathbf{u}' \in bin(\mathbf{u})} A(\mathbf{W}^{-1}(\mathbf{u}'; \mathbf{p}); \boldsymbol{\lambda}) d\mathbf{u}'$$

Discrete implementation:

$$B(\mathbf{u}; A(\mathbf{W}(\mathbf{p}); \boldsymbol{\lambda})) = \frac{1}{area(\mathbf{u})} \sum_{\mathbf{x} \in s_0 \text{ s.t.}} A(\mathbf{x}; \boldsymbol{\lambda}) |J(\mathbf{W}(\mathbf{p}))|$$

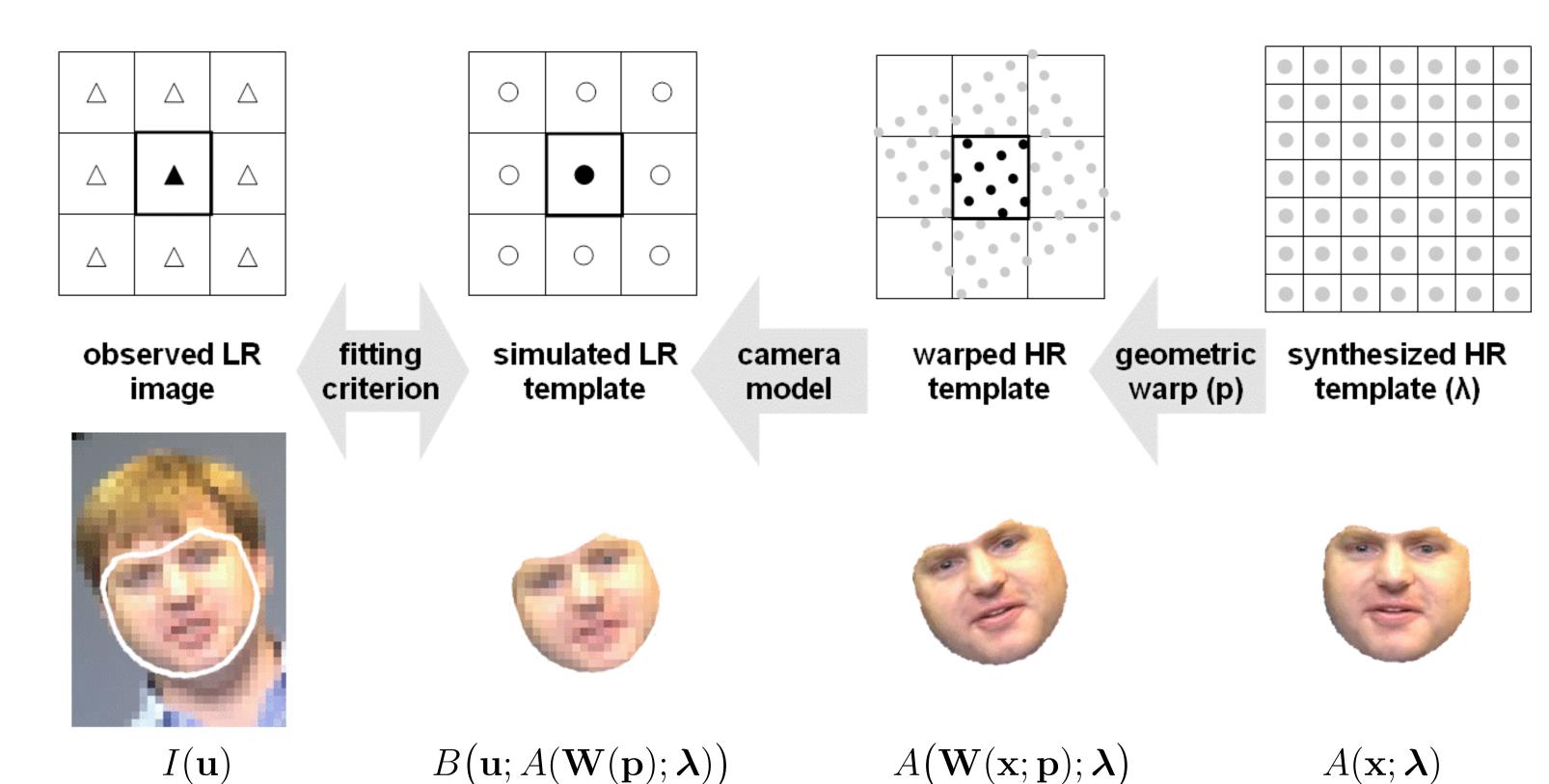
$$\mathbf{u} - \begin{bmatrix} .5 \\ .5 \end{bmatrix} < \mathbf{W}(\mathbf{x}; \mathbf{p}) < \mathbf{u} + \begin{bmatrix} .5 \\ .5 \end{bmatrix}$$

Gauss-Newton gradient descent:

$$\begin{pmatrix} \Delta \mathbf{p} \\ \Delta \boldsymbol{\lambda} \end{pmatrix} = -H_{sim}^{-1} \sum_{\mathbf{u} \in I} B(\mathbf{u}; \mathbf{S} \mathbf{D}_{sim}^{\mathrm{T}}) \left[ I(\mathbf{u}) - B(\mathbf{u}; A_0(\mathbf{W}(\mathbf{p}))) + \sum_{i=1}^{m} \lambda_i B(\mathbf{u}; A_i(\mathbf{W}(\mathbf{p}))) \right]$$

$$\mathbf{SD}_{sim} = \left[ \left( \nabla A_0 + \sum_{i=1}^m \lambda_i \nabla A_i \right) \frac{\partial \mathbf{W}}{\partial p_1}, ..., \left( \nabla A_0 + \sum_{i=1}^m \lambda_i \nabla A_i \right) \frac{\partial \mathbf{W}}{\partial p_n}, A_1 (\mathbf{W}(\mathbf{p})), ..., A_m (\mathbf{W}(\mathbf{p})) \right]$$

$$H_{sim} = \sum_{\mathbf{u} \in I} B(\mathbf{u}; \mathbf{SD}_{sim}^T) B(\mathbf{u}; \mathbf{SD}_{sim})$$



The Resolution-Aware Fitting algorithm simulates the formation of low resolution images in a digital camera. In contrast to the traditional formulation, the fitting criterion is defined between observed and simulated image pixels.

#### Computational Comparison

- AAMR-SIM can pre-compute steepest-descent images and Hessians, leading to very efficient tracker implementations.
- RAF gives up the computational efficiency of AAMR-SIM in exchange for a more accurate/unbiased estimate of the parameters. Gradient-descent parameters need to be recomputed at every iteration.

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tracked

landmarks

tracking

hand-labeled

landmarks

similarity +

non-rigid

deformation

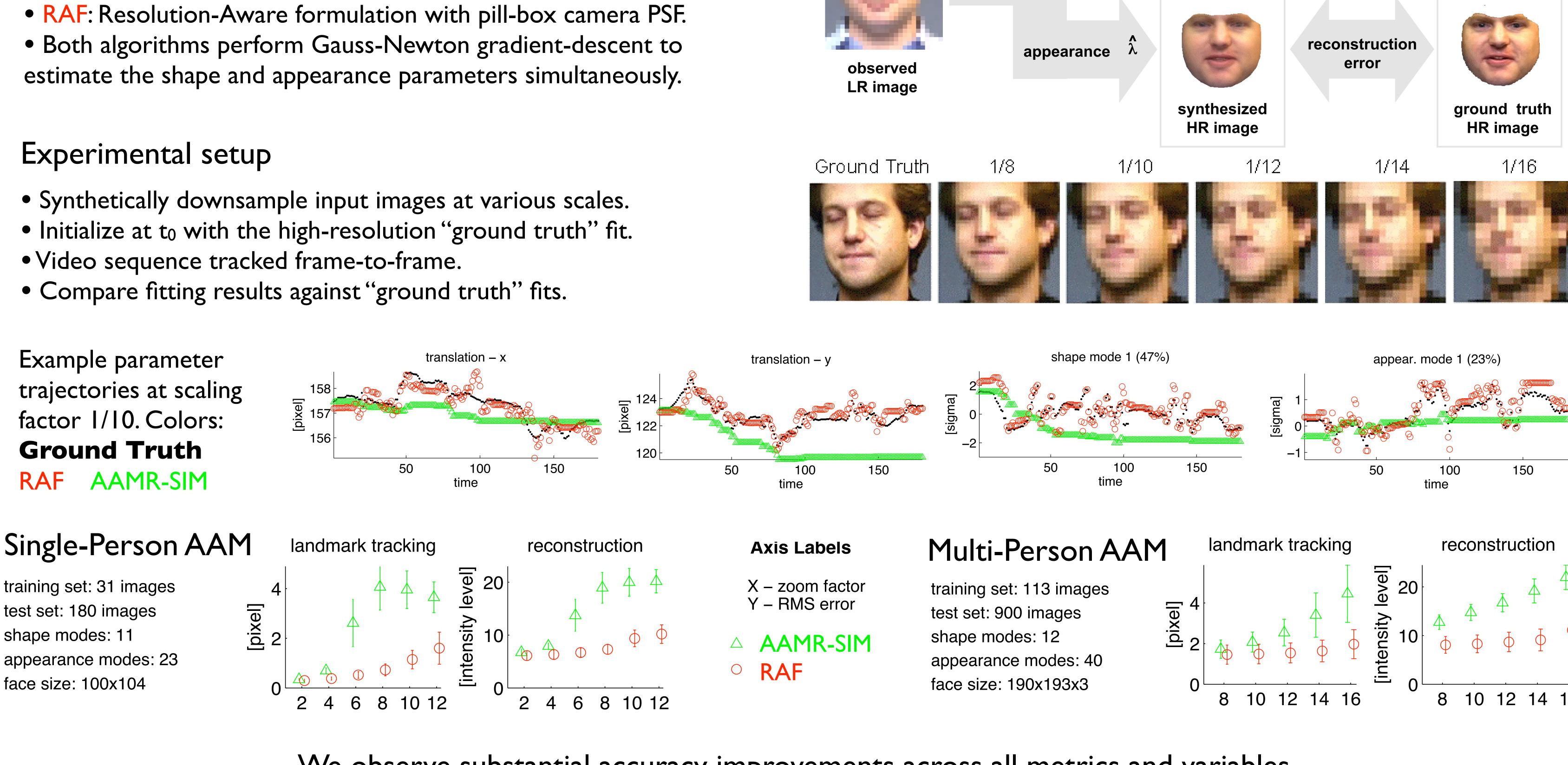
fitting

algorithm

## Quantitative Results

#### Algorithms and Accuracy Metrics

• AAMR-SIM: Traditional formulation.

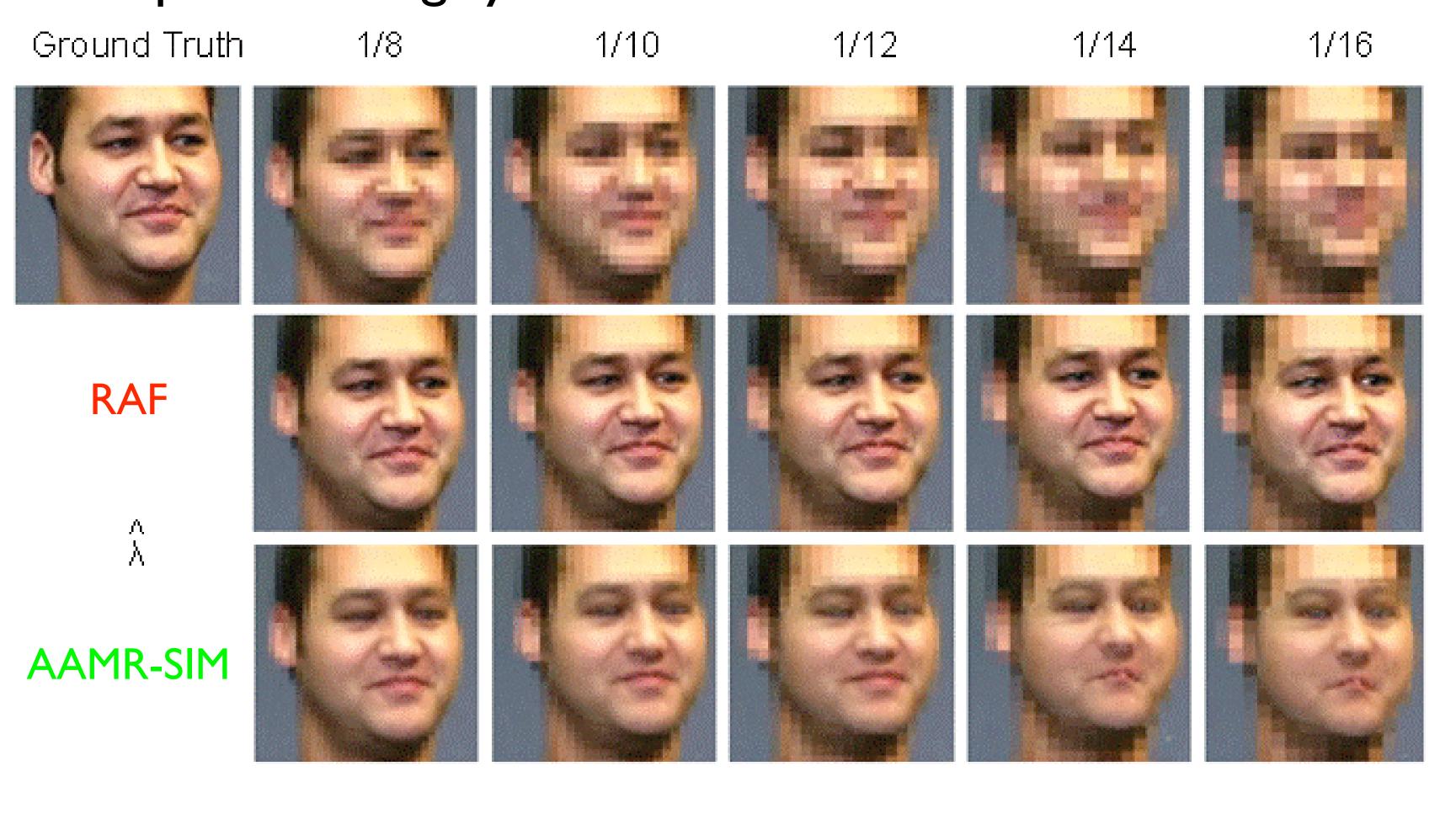


We observe substantial accuracy improvements across all metrics and variables.

## Qualitative Results

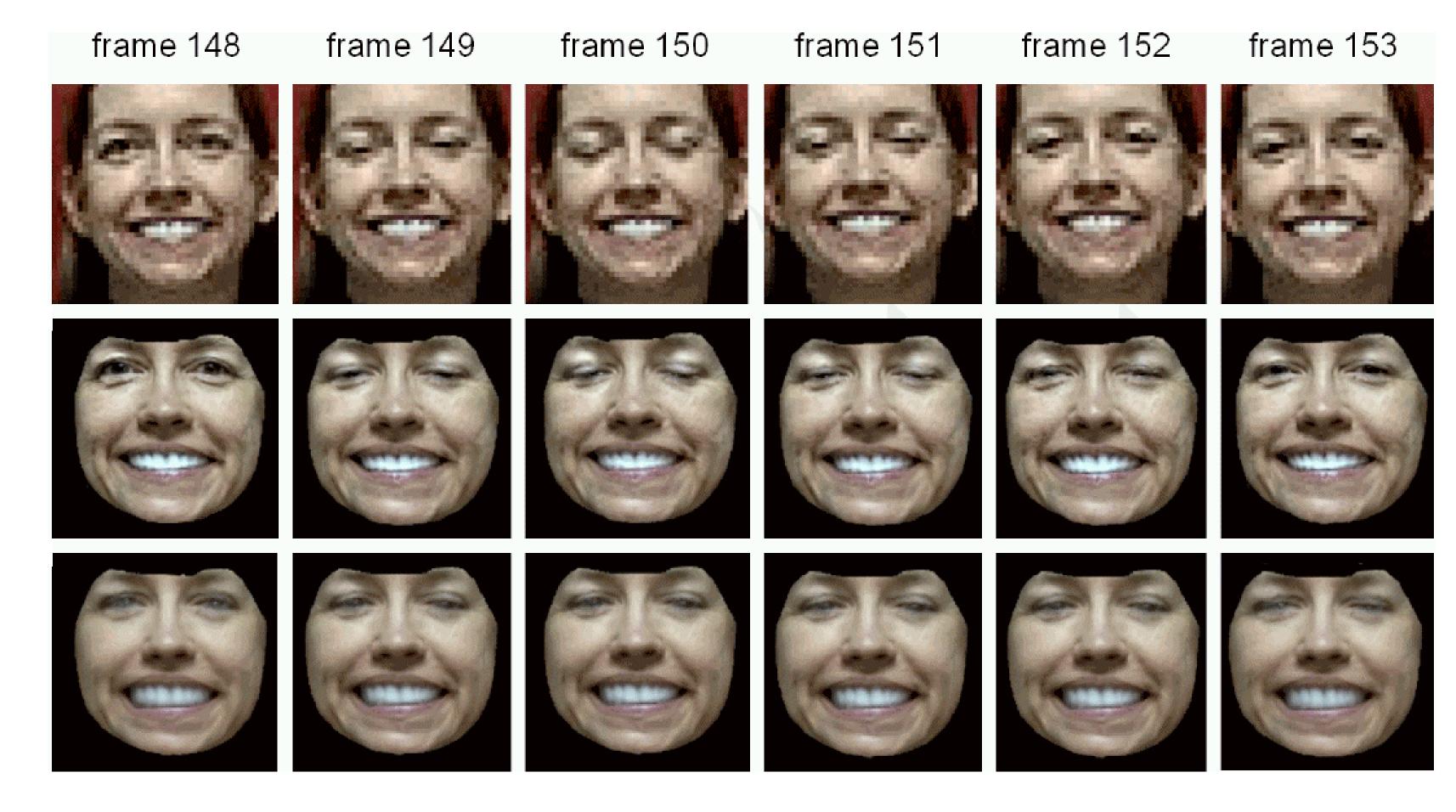
videos: http://www.cs.cmu.edu/~dedeoglu/eccv06

Example fits using synthetic low-resolution data.



#### Example fits using DV-compressed real low-resolution data

- Single-person AAM built at 110x114 pixel resolution.
- Shown below: eye-blink sequence, scaling ~1/3.
- RAF correctly recovers the eye-blink, whereas AAMR-SIM does not.



Resolution-Aware Fitting results remain visually detailed and realistic despite input resolution degradation.

## Conclusion

- In low-resolution regimes, traditional AAM fitting algorithms suffer from an artifact of formulation. Since they rely on interpolation, their accuracy degrades quickly. The proposed Resolution-Aware Formulation avoids interpolation, and uses a camera (blur) model instead. This leads to significant accuracy improvements.
- In [Dedeoglu et al., '06], we argue that image-based warp estimation is an asymmetric problem. In the presence of relative scaling, the warp direction ought to be chosen such that the higher-resolution image gets pre-blurred and warped onto the lower-resolution one. As such, the Resolution-Aware Fitting algorithm is an application of this principle.

#### References

- T.F. Cootes, G.J. Edwards, and C.J. Taylor: Active Appearance Models. Proc. of the European Conference on Computer Vision, Vol. 2, 1998, pp. 484-498.
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- R. Gross, I. Matthews, and S. Baker: Generic vs. Person-Specific Active Appearance Models. Image and Vision Computing, Vol. 23, No. 11, Nov., 2005, pp. 1080-1093.
- G. Dedeoglu, T. Kanade, and S. Baker: The Asymmetry of Image Registration and its Application to Face Tracking. submitted to IEEE Trans. on PAMI, under review, available as Technical Report CMU-RI-TR-06-06.

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